

# MikroKopter-Setting

Kanäle	ARF		
	Funktion	KopterTool – Einstellungen	Sender – Belegung
Ch1	Gas	Kanäle > GAS > Ch1	Stick links (up/down)
Ch2	Roll	Kanäle > ROLL > Ch2	Stick rechts (left/right)
Ch3	Nick	Kanäle > NICK > Ch3	Stick rechts (up/down)
Ch4	Gier	Kanäle > Gier > Ch4	Stick links (left/right)
Ch5	Auto-Höhenregelung	EasySetup > Höhenregelung aktiv > Ch5	2-fach Schalter
Ch6	GPS	EasySetup > GPS > Ch6	3-fach Schalter
Ch7	Servo3 (CamCtrl-Zoom)	Kamera > Servo 3 > Poti3	Poti
Ch8	CareFree (Headless Mode)	EasySetup > Carefree Steuerung > Ch7	2-fach Schalter
Ch9	Kamera Nick	Kamera > Servo Ansteuerung – Nick > Poti5	Poti
Ch10	Kamera Roll	Kamera > Servo Ansteuerung – Roll > Poti6	Poti
Ch11	Kamera trigger CamCtrl (off-trigger-rec)	Ausgang > Ausgang1 Timing > Poti7 + Kamera > Servo 4 > Poti7	Taster 3-fach Schalter
Ch12	Motor-Sicherheitsschalter	Kanäle > Motor-Sicherheitsschalter > Ch12	Taster
Ch13			
Ch14			
Ch15			
Ch16			

Channel	ARF		
	Function	KopterTool – Setting	Transmitter – assignment
Ch1	throttle (Gas)	Channels > GAS > Ch1	Stick left (up/down)
Ch2	Roll	Channels > ROLL > Ch2	Stick right (left/right)
Ch3	Nick	Channels > NICK > Ch3	Stick right (up/down)
Ch4	Yaw	Channels > Yaw > Ch4	Stick left (left/right)
Ch5	AltitudeControl	EasySetup > Enable Altitude control > Ch5	2-way Switch
Ch6	GPS	EasySetup > GPS > Ch6	3-way Switch
Ch7	Servo3 (CamCtrl-Zoom)	Camera > Servo 3 > Poti3	Poti
Ch8	CareFree (Headless Mode)	EasySetup > Carefree control > Ch7	2-way Switch
Ch9	Camera nick	Camera > Servo control – Nick > Poti5	Poti
Ch10	Camera Roll	Camera > Servo control – Roll > Poti6	Poti
Ch11	Camera trigger CamCtrl (off-trigger-rec)	CamCtrl > Out1 Timing > Poti7 + Camera > Servo 4 > Poti7	Push button 3-way Switch
Ch12	Motor safety switch	Channels > Motor safety switch > Ch12	Push button
Ch13			
Ch14			
Ch15			
Ch16			

## Extra

KopterTool > Einstellungen

Kanäle > Poti1 > Ch5  
Poti2 > Ch6  
Poti3 > Ch7  
Poti4 > Ch8  
Poti5 > Ch9  
Poti6 > Ch10  
Poti7 > Ch11  
Poti8 > Ch12  
Motor-Sicherheitsschalter > Ch12

Motor-Start => Motor-Sicherh.Taster ziehen PLUS Gas unten + Gier rechts  
Motor-Stop => Motor-Sicherh.Taster ziehen PLUS Gas unten + Gier links

Info: Ch12 für den Motor-Sicherheitsschalter muss in Sender invertiert werden!



## Extra

KopterTool > Settings

Channels > Poti1 > Ch5  
Poti2 > Ch6  
Poti3 > Ch7  
Poti4 > Ch8  
Poti5 > Ch9  
Poti6 > Ch10  
Poti7 > Ch11  
Poti8 > Ch12  
Motor safety switch > Ch12

Motor-Start => Motor safety switch PLUS throttle down + yaw right  
Motor-Stop => Motor safety switch PLUS throttle down + yaw left

INFO: Invert Ch12 for the Motor safety switch on your transmitter!

